



Universitat de Lleida

DEGREE CURRICULUM

INDUSTRIAL AUTOMATION

Coordination: GUIRADO FERNÁNDEZ, FERNANDO

Academic year 2021-22

Subject's general information

| | | | | |
|---|--|---------------|------------------------|------------------|
| Subject name | INDUSTRIAL AUTOMATION | | | |
| Code | 102115 | | | |
| Semester | 2nd Q(SEMESTER) CONTINUED EVALUATION | | | |
| Typology | Degree | Course | Character | Modality |
| | Bachelor's Degree in Automation and Industrial Electronic Engineering | 2 | COMPULSORY | Attendance-based |
| | Bachelor's Degree in Energy and Sustainability Engineering | 2 | COMPULSORY | Attendance-based |
| | Bachelor's Degree in Mechanical Engineering | 2 | COMPULSORY | Attendance-based |
| | Double bachelor's degree: Degree in Mechanical Engineering and Degree in Energy and Sustainability Engineering | 2 | COMPULSORY | Attendance-based |
| | Master's Degree in Industrial Engineering | 1 | COMPLEMENTARY TRAINING | Attendance-based |
| Not informed | 2 | COMPULSORY | Attendance-based | |
| Course number of credits (ECTS) | 6 | | | |
| Type of activity, credits, and groups | Activity type | PRALAB | | TEORIA |
| | Number of credits | 3 | | 3 |
| | Number of groups | 4 | | 2 |
| Coordination | GUIRADO FERNÁNDEZ, FERNANDO | | | |
| Department | COMPUTER SCIENCE AND INDUSTRIAL ENGINEERING | | | |
| Teaching load distribution between lectures and independent student work | 40% lectures 60% autonomous work | | | |

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|---|---|
| Important information on data processing | Consult this link for more information. |
| Language | Català |
| Distribution of credits | 20% theoretical content 30% classroom activities 50% laboratory |

| Teaching staff | E-mail addresses | Credits taught by teacher | Office and hour of attention |
|-----------------------------|--------------------------|---------------------------|------------------------------|
| GUIRADO FERNÁNDEZ, FERNANDO | fernando.guirado@udl.cat | 9 | |
| MATEO FORNÉS, ADRIÀ | adria.mateo@udl.cat | 9 | |

Subject's extra information

Most practical course in which the study is based on problem solving and recommended mandatory. It is essential for personal work skills set and gain the skills to properly use the tools that work with the course.

Materials can be found on the Virtual Campus: <http://cv.udl.cat>

The use of Virtual Campus access to resources is fundamental to the subject, the notifications delivery dates workout, schedule meetings and finally delivering practical assessment tests.

Learning objectives

- Acquire knowledge about the fundamentals of automation and methods of control.
- Determine the transfer function of dynamic electrical systems.
- Explain the concept of an open loop control system and closed loop and identify the elements that make up them.
- Understand the meaning of the concepts of Control System and Industrial Process, understanding its relation.
- Know how to design simple wiring automation.
- Understand the internal architecture of a PLC and the its cycle of operation.
- Know the components of the GRAFCET diagrams.
- Know how to design a GRAFCET that implements a sequential industrial process.
- Know how to program and debug a PLC.

Competences

Specific competences

GEM12/GEEIA12/CG12. Knowledge of the basics of automatisms and control methods.

CE10. Have knowledge of the principles of automatic regulation and its application to industrial automation.

CE14. Acquire the ability to design industrial automation and control systems.

Cross-disciplinary competences

EPS1/CB2. Capacity to solve problems and prepare and defence arguments inside the area of studies.

EPS7. Capacity to work in situations with a lack of information and/or under pressure.

Subject contents

1. Sensors and actuators
 - 1.1 Transducers - Classification
 - 1.2 Signal transmission
 - 1.3 Dynamic and static characteristics
 - 1.4 Types of sensors
2. Automatic regulation.
 - 2.1 Introduction to automatic regulation
 - 2.2 Dynamic systems
 - 2.3 Feedback control systems
 - 2.4 Regulators
 - 2.5 Control structures
 - 2.6 Classification of the industrial processes
3. Wired automations.
 - 3.1 Introduction
 - 3.2 Power and maneuvering devices
 - 3.3 Power circuit and maneuver
4. Scheduled automations.
 - 4.1 Introduction
 - 4.2 Control systems
 - 4.3 Programmable Logic Controller (PLC)
 - 4.4 Human-Machine Interfaces (HMI)
 - 4.4 PLC programming
5. Sequential processes: GRAFCET
 - 5.1 Introduction
 - 5.2 Components
 - 5.3 Structures
 - 5.4 Rules of evolution
 - 5.5 Special control structures

Methodology

This subject combines theoretical and problem sessions as well as practical exercises and laboratory work.

Most of the practical activities will be developed individually although the projects must be carried out in work

teams made up of 2 students.

Methodology used:

- Master classes in videoconference format where the basic concepts of the contents will be explained.
- Classes of problems in videoconference format where exercises related to the master classes will be developed.
- Laboratory practices developing and expanding concepts of the different topics.
- All activities involve student autonomous work

The follow-up of the subject will be done through the delivery of exercises worked in the class sessions or independently through the Virtual Campus. Questionnaires will also be carried out in online format.

In addition, students will have the responsibility to reinforce their knowledge in a way autonomous based on the teaching material provided or recommended by the teacher.

Development plan

| Week | Content | Scheduling |
|------|---------------------------------|---|
| 1 | 1. Lecture class and exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 2 | 2. Lecture class and exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 3 | 2. Exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 4 | 2. Exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 5 | 3. Lecture class and exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 6 | 3. Practices | 2h online / 2h Lecture class / 6h Autonomous work |
| 7 | 3. Practices | 2h online / 2h Lecture class / 6h Autonomous work |
| 8 | 3. Practices | 2h online / 2h Lecture class / 6h Autonomous work |
| 9 | Midterm-evaluation | |
| 10 | 4. Lecture class and exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 11 | 4. Practices | 2h online / 2h Lecture class / 6h Autonomous work |
| 12 | 4. Practices | 2h online / 2h Lecture class / 6h Autonomous work |
| 13 | 5. Lecture class and exercises. | 2h online / 2h Lecture class / 6h Autonomous work |
| 14 | 5. Practices | 2h online / 2h Lecture class / 6h Autonomous work |
| 15 | 5. Practices | 2h online / 2h Lecture class / 6h Autonomous work |

Evaluation

The grade of the subject consists of the following sections

- Theory / problems (evaluation by examination)

First mid-term * - 15%

Second mid-term * - 15%

- Online questionnaires for each topic * - 10%

- 4 Laboratory activities (5% each) - 20%

- A hard-wired project - 20%

- A sequential project - 20%

The recovery activity will correspond to a single re-evaluation exam that will include the contents of the elements marked with an * and will correspond to 40% of the mark. The other 60% will come from the laboratory activities and the projects grade.

(1) Attendance at the laboratory is mandatory at the assigned group

Bibliography

[1] Autómatas Programables. Joseph Balcells, J. L. Romeral, Ed. Marcombo – Serie Mundo Electrónico, ISBN 84-267-1089-1

[2] Automatización. Problemas Resueltos con Autómatas Programables. L. Pedro Romera, J. Antonio Lorite, Sebastián Montoso, Editorial Paraninfo, ISBN 84-283-2077-2

[3] Automatización con GRAFCET, Múltiples autores, Servicio de publicaciones – Universidad de Málaga, ISBN – 84-7496-724-4

[4] Dorf, Richard C. Sistemas modernos de control. 2ª ed. en esp.. Argentina, [etc.]: Addison-Wesley Iberoamericana, 1989. ISBN 0201644177 (ADDISON WESLEY)

[5] Ogata, Katsuhiko. Ingeniería de control moderna. 5a ed.. Madrid [etc.]: Pearson Educación, cop. 2010. ISBN 9788483226605.

[6] Groover, Mikell P. Automation, production systems and computer-integrated manufacturing. 3rd ed.. Upper Saddle River, NJ: Prentice Hall, c2008. ISBN 9780132070737.