



Universitat de Lleida

DEGREE CURRICULUM  
**THEORY OF MECHANISMS**

Academic year 2015-16

## Subject's general information

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|---|--|
| <b>Subject name</b>   | Theory of Mechanisms   |
| <b>Code</b>   | 102110   |
| <b>Semester</b>   | 1st semester   |
| <b>Typology</b>   | Mandatory  |
| <b>ECTS credits</b>   | 6  |
| <b>Theoretical credits</b>  | 3  |
| <b>Practical credits</b>  | 3  |
| <b>Office and hour of attention</b>   | Joan Roca Enrich Monday, 12 to 13. Wednesday, 17 to 18<br>Martí Comellas Andrés Monday, 17 to 18. Thursday, 12 to 13<br>Xavier Terribas Sala |
| <b>Department</b>   | Informàtica i Enginyeria Industrial  |
| <b>Teaching load distribution between lectures and independent student work</b> | Face to face: 40 %<br>Autonomous work: 60 %  |
| <b>Modality</b>   | Presencial   |
| <b>Important information on data processing</b>                                 | Consult <a href="#">this link</a> for more information.  |
| <b>Language</b>   | Catalan  |
| <b>Degree</b>   | Degree in Mechanical Engineering and Degree in Industrial Electronics and Automation Engineering   |
| <b>Office and hour of attention</b>   | Joan Roca Enrich Monday, 12 to 13. Wednesday, 17 to 18<br>Martí Comellas Andrés Monday, 17 to 18. Thursday, 12 to 13<br>Xavier Terribas Sala |
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Joan Roca Enrich  
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## Subject's extra information

The main background needed to take advantage of the subject are: operations with vectors, trigonometry, derivatives and integrals of one variable, graphical representation of multi-body systems, dynamics of a mass particle

It is essential to have studied previously, and it is advisable to have passed the following subjects:

- Linear Algebra
- Calculus
- Physics I
- Graphics Expression I

## Learning objectives

See competences.

## Competences

### Degree specific competences

- Knowledge of the principles of theory of machines and mechanisms.

### Cross-disciplinary competences

- Capacity to gather and interpret relevant data, within the area of study, to judge and think about relevant subjects of social, scientific and ethical nature..
- Capacity to solve problems and prepare and defence arguments inside the area of studies.
- Capacity to work in situations with a lack of information and/or under pressure.

## Subject contents

1. Rigid body kinematics
2. Rigid body dynamics: momentum and angular momentum
3. Introduction to mechanisms
4. Mobility of mechanisms
5. Mechanism kinematics

6. Mechanism dynamics: vectorial theorems
7. Energy theorem applied to mechanism dynamics

## Methodology

Theory classes: Presentations are available in SAKAI before class starts.

Problems classes: Solving problems, questions and exercises. Some solved exercises are available in SAKAI

3 laboratory sessions will take place during the semester, one using a CAD software and two at the mechanical laboratory, in the CREA building. Attendance at laboratory practices is mandatory.

Throughout the semester, students will have to carry out 2 works in groups of 3 or 4 students. They will consist in the kinematic or dynamic analysis of a mechanical system.

## Evaluation

There will be some different evaluation activities:

- 1st individual written exam
- Reports from the laboratory sessions
- Works in group
- 2nd individual written exam, with a minimum mark of 3 over 10 to be able to pass the subject
- Make-up exam of the 2nd individual one, with the same minimum mark

The percentage assigned to each evaluation activity, of total of 100, is as follows:

| Activity                               | Percentage |
|--|------------|
| 1st individual exam                    | 20         |
| Laboratory sessions                    | 10         |
| Work in group                          | 10+10      |
| 2nd individual exam                    | 50         |
| Make-up exam of the 2nd individual one | 50         |

## Bibliography

- BEDFORD, A. & FOWLER, W. (1996) *Mecánica para Ingeniería. Dinámica*. Addison-Wesley Iberoamericana.E.U.A.
- BEER, F.P. & JOHNSTON, E.R. (1998) *Mecánica Vectorial para ingenieros. Dinámica*. McGraw Hill.
- HIBBELER, R.C.(1996) *Ingeniería Mecánica. Dinámica*.Prentice-Hall Hispanoamericana. México.
- MERIAM, J.L. & KRAIGE, L.G.(1998) *Engineering Mechanics. Dynamics*.John Wiley & Sons. USA.
- MYSZKA,D. (1998) *Machines and Mechanisms. Applied Kinematic Analysis*. Prentice Hall. New Jersey.
- CARDONA, S. et al. (1998) *Teoría de Màquines*. Ed. CPDA-ETSEIB.Barcelona.
- MABIE, H & REINHOLTZ, C. (1998) *Mecanismos y Dinámica de Maquinaria*. Limusa.México.
- RIBA, C. (1995) *Dissenyde Màquines I. Mecanismes*. Edicions UPC. Barcelona.
- NORTON, R.L. (1995) *Diseño de Maquinaria*. McGraw Hill. México.
- SHIGLEY & MISCHKE.*Diseño en Ingeniería Mecánica*. McGraw Hill.